

EECS 120
Final Exam
Thur. Dec. 18, 2014
0810 - 1100 am

Name: _____

SID: _____

- Closed book. Three single sided 8.5x11 inch pages of formula sheet. No calculators.
- There are 8 problems worth 200 points total. There may be more time efficient methods to solve problems.

| Problem | Points | Score |
|---------|--------|-------|
| 1 | 26 | |
| 2 | 40 | |
| 3 | 12 | |
| 4 | 20 | |
| 5 | 36 | |
| 6 | 36 | |
| 7 | 30 | |
| TOTAL | 200 | |

In the real world, unethical actions by engineers can cost money, careers, and lives. The penalty for unethical actions on this exam will be a grade of zero and a letter will be written for your file and to the Office of Student Conduct.

| | |
|--------------------------------------|---|
| $\tan^{-1} 0.1 = 5.7^\circ$ | $\tan^{-1} 0.2 = 11.3^\circ$ |
| $\tan^{-1} \frac{1}{2} = 26.6^\circ$ | $\tan^{-1} 1 = 45^\circ$ |
| $\tan^{-1} \frac{1}{3} = 18.4^\circ$ | $\tan^{-1} \frac{1}{4} = 14^\circ$ |
| $\tan^{-1} \sqrt{3} = 60^\circ$ | $\tan^{-1} \frac{1}{\sqrt{3}} = 30^\circ$ |
| $\sin 30^\circ = \frac{1}{2}$ | $\cos 60^\circ = \frac{\sqrt{3}}{2}$ |
| $\cos 45^\circ = \frac{\sqrt{2}}{2}$ | $\sin 45^\circ = \frac{\sqrt{2}}{2}$ |

| | | |
|--------------------------------------|-----------------------------------|---------------------------|
| $20 \log_{10} 1 = 0dB$ | $20 \log_{10} 2 = 6dB$ | $\pi \approx 3.14$ |
| $20 \log_{10} \sqrt{2} = 3dB$ | $20 \log_{10} \frac{1}{2} = -6dB$ | $2\pi \approx 6.28$ |
| $20 \log_{10} 5 = 20dB - 6dB = 14dB$ | $20 \log_{10} \sqrt{10} = 10 dB$ | $\pi/2 \approx 1.57$ |
| $1/e \approx 0.37$ | $\sqrt{10} \approx 3.164$ | $\pi/4 \approx 0.79$ |
| $1/e^2 \approx 0.14$ | $\sqrt{2} \approx 1.41$ | $\sqrt{3} \approx 1.73$ |
| $1/e^3 \approx 0.05$ | $1/\sqrt{2} \approx 0.71$ | $1/\sqrt{3} \approx 0.58$ |

$$\begin{aligned} \cos 2\theta &= \cos^2 \theta - \sin^2 \theta & \sin 2\theta &= 2 \sin \theta \cos \theta \\ e^{j\theta} &= \cos \theta + j \sin \theta & \sin^2 \theta + \cos^2 \theta &= 1 \end{aligned}$$

Problem 1 LTI Properties (26 pts)

[24 pts] Classify the following systems, with input $x(t)$ (or $x[n]$) and output $y(t)$ (or $y[n]$). In each column, write “yes”, “no”, or “?” if the property is not decidable with the given information. (+1 for correct, 0 for blank, -0.5 for incorrect). (For 1d, you are given the system is known to be linear and time-invariant.) For 1b and 1d, 2 test input cases are given.

Let $\Pi(t) = u(t + \frac{1}{2}) - u(t - \frac{1}{2})$

| System | Causal | Linear | Time-invariant | BIBO stable |
|--|--------|--------|----------------|-------------|
| a. $y(t) = 2x(t - 1) - 5$ | | | | |
| b. If $x(t) = 0 \rightarrow y(t) = 0$. If $x(t) = u(t - 1) \rightarrow y(t) = tu(t)$. | | | | |
| c. $y(t) = x(t)[\cos(2\pi t)u(t)]$ | | | | |
| d. If $x(t) = 0 \rightarrow y(t) = 0$ If $x(t) = u(t) \rightarrow y(t) = u(t - 1)$ | | YES | YES | |
| e. $y(t) = \int_{\tau=-\infty}^{\infty} x(\tau)\Pi(t - \tau)d\tau$ | | | | |
| f. $y(t) = x(t) \cdot [1 - \delta(t + 100)]$ | | | | |
| g. $y[n] = \mathcal{Z}^{-1}\{\frac{z^2}{z+1}\} * x[n]$ | | | | |

Problem 2 Short Answers (40 pts)

Answer each part independently. Note $\Pi(t) = u(t + \frac{1}{2}) - u(t - \frac{1}{2})$.

[4 pts] a. Complete the table with the appropriate type of Fourier transform to use (FS, FT, DTFT, or DFT) on a signal of each type.

| | aperiodic in time | periodic in time |
|-----------------|-------------------|------------------|
| continuous time | | |
| discrete time | | |

[3 pts] b. $X(j\omega) = \cos(\omega/2) + 1$. Find $x(t)$.

$x(t) =$ _____

[4 pts] c. A periodic signal $x(t) = p(t) * \sum_{n=-\infty}^{\infty} \delta(t - 2n)$, where $\mathcal{F}\{p(t)\} = P(j\omega) = \cos(\omega/2) + 1$. The fundamental period $\omega_o = \pi$. Find the Fourier series coefficients a_k .

$a_k =$ _____

[7 pts] d. A periodic signal $x(t)$ has period 4 seconds and Fourier Series coefficients $a_k = \frac{\sin(k\pi/4)}{k\pi}$. Find the time average power $\frac{1}{T} \int_T x^2(t) dt$.

time average power = _____

[9 pts] e. Initial and final value.

i. Given $X(s) = \frac{s+3}{s^2+3s+2}$. Find $x(0^+) =$ _____

ii. Given causal $X(z) = \frac{z^{-2}+2z^{-3}}{1-2z^{-1}+\frac{5}{4}z^{-2}-\frac{1}{4}z^{-3}}$.

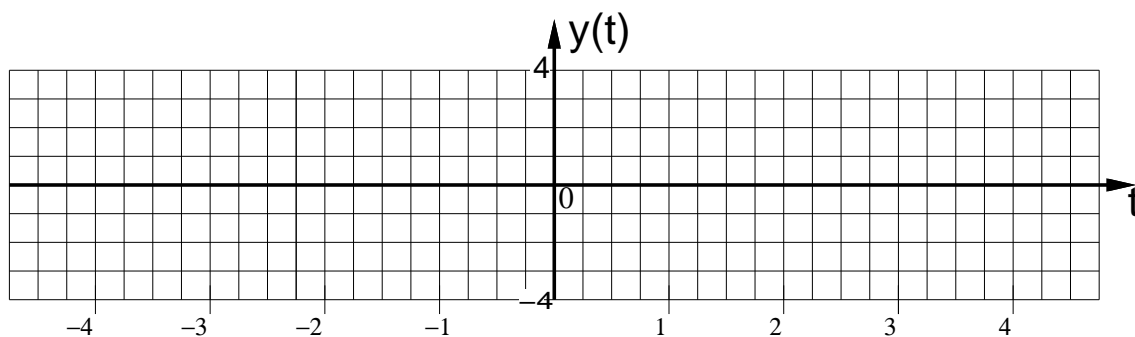
Find $\lim_{n \rightarrow \infty} x[n] =$ _____

iii. Given causal $X(z) = \frac{2+3z^{-1}}{1-2z^{-1}+\frac{5}{4}z^{-2}-\frac{1}{4}z^{-3}}$.

Find $x[0] =$ _____

[5 pts] f. Given causal $X(s) = \frac{s+5}{s^3+3s^2+2s}$. Find $x(t) =$ _____

[8 pts] g. Sketch $y(t) = 3\pi \cdot u(t+1) * \cos(\pi t)u(t)$



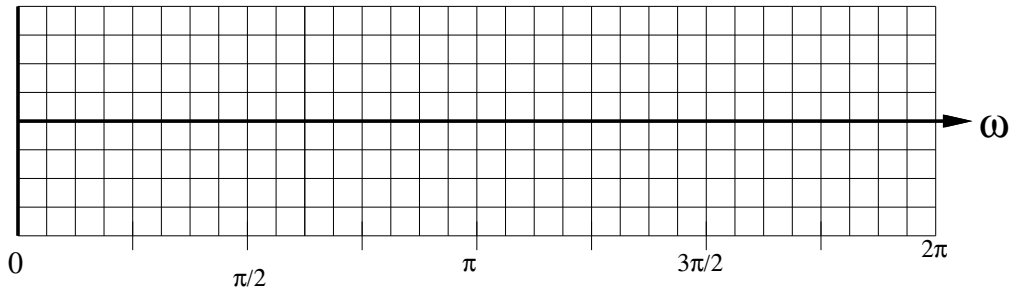
Problem 3. Digital Filter (12 pts)

A continuous time filter has impulse response $h(t) = e^{-\pi t/2}u(t)$.

[6 pts] a. The filter is sampled such that $h[n] = h(nT_s)$ where the sampling rate $T_s = 1$ sec. Find the Z transform of $h[n]$.

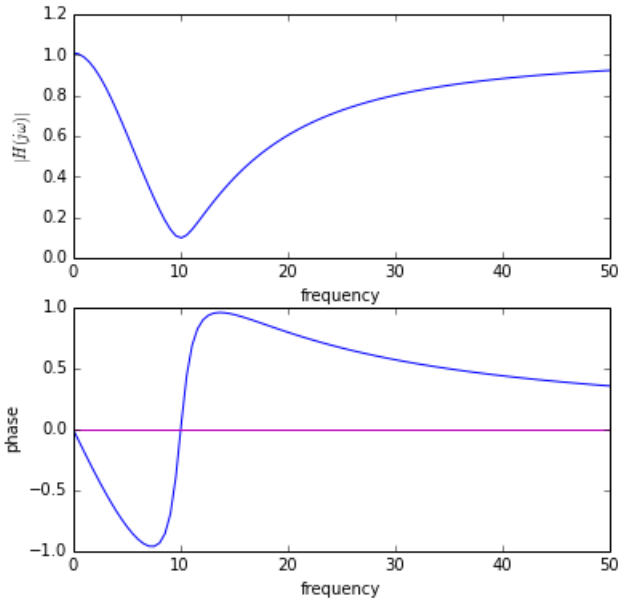
$H(z) = \underline{\hspace{2cm}}$

[6 pts] b. Sketch $|H(e^{j\omega})|$, labelling maximum and minimum amplitude. (Maximum and minimum may be left as functions of e).

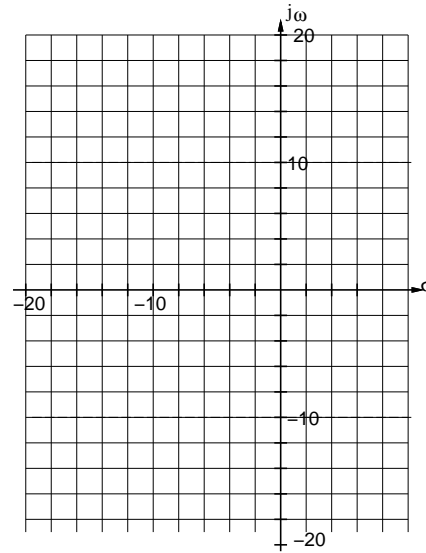


Problem 4. CT and Digital Filters (20 pts)

[10 pts] a. The magnitude and phase response for a continuous time, real, causal, stable LTI system is shown below. Sketch a pole-zero diagram for a stable system (using minimum number of poles and zeros) which would match the given magnitude and phase response.

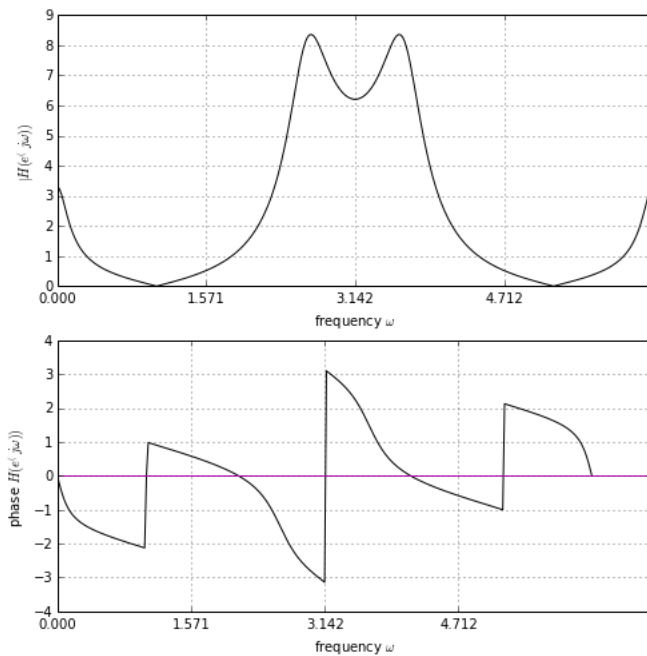


Given magnitude and phase.

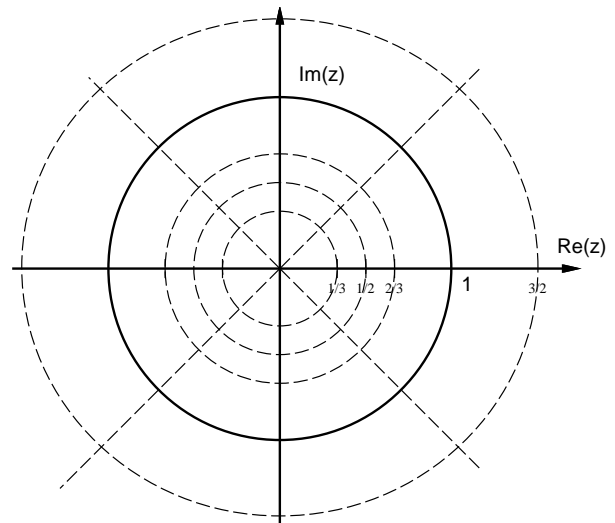


Sketch corresponding pole-zero plot here.

[10 pts] b. The magnitude and phase response for a discrete time, real, causal, stable LTI system is shown below. Sketch a pole-zero diagram for a stable system (using minimum number of poles and zeros) which would match the given magnitude and phase response. (Note: the phase change at π is just numerical wrapping.)



Given magnitude and phase.



Sketch corresponding pole-zero plot here.

Problem 5. Z transform (36 pts)

Consider a causal DT system with

$$H(z) = \frac{z^2 + 9/4}{z(z - \frac{1}{2})}$$

[4 pts] a. Find the unit sample response $h[n]$ for $H(z)$.

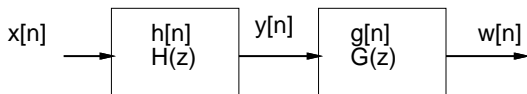
$h[n] =$ _____

[4 pts] b. With input $x[n]$ and output $y[n]$, find the linear difference equation in terms of $y[n]$ for this system:

$y[n] =$ _____

[4 pts] c. $H(z)$ is not minimum phase. Find a minimum phase function $F(z)$ such that $|H(e^{j\omega})| = |F(e^{j\omega})|$ for all ω .

$F(z) =$ _____

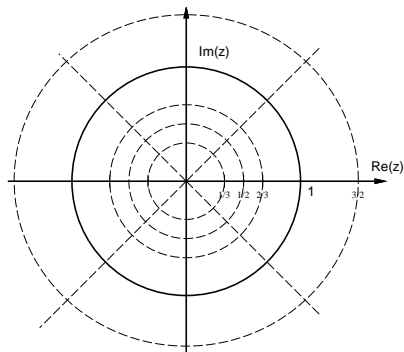
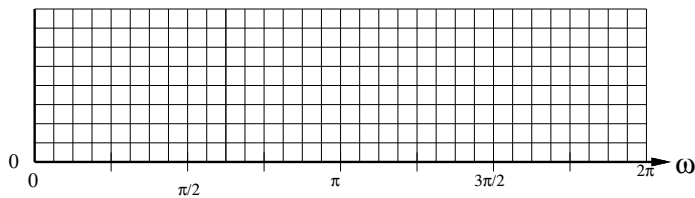


[4 pts] d. Find a **stable** $G(z)$ such that $|H(e^{j\omega})G(e^{j\omega})| = 1$ for all ω .

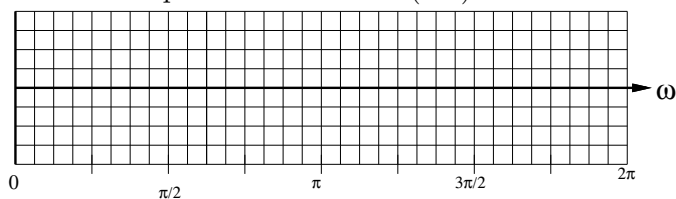
$G(z) =$ _____

[12 pts] e. VERSION 2 Approximately sketch $|H(e^{j\omega})|$ [4 pts] and phase of the zeros *only* of $H(e^{j\omega})$ [8 pts] on the plots below, noting key maxima and minima.

$|H(e^{j\omega})|$:



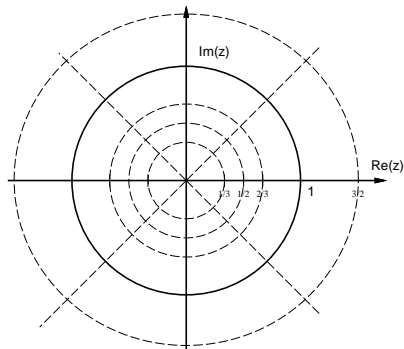
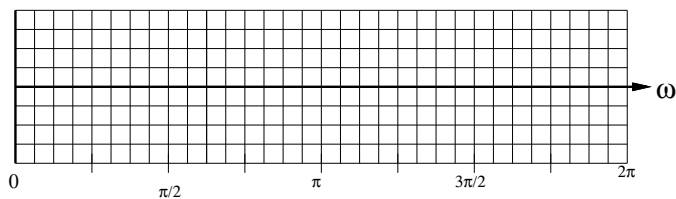
phase of zeros of $H(e^{j\omega})$:



scratch work area

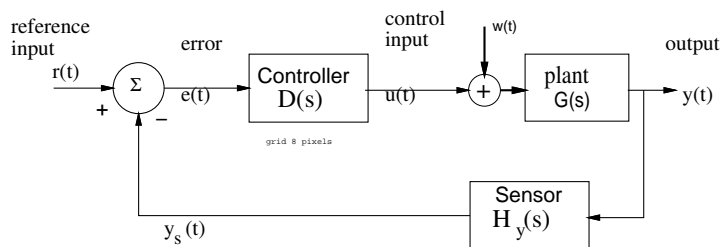
[8 pts] f. VERSION 2 Sketch the phase due to the zeros of $F(e^{j\omega})$ on the plot below, noting key maxima and minima. (Hint: sketch phase from each zero independently, then add.)

$\angle F(e^{j\omega})$:



scratch work area

Problem 6. Control (36 pts)



[2 pts] a. Find the transfer function $\frac{E(s)}{W(s)}$ in terms of D, G, H_y .

$$\frac{E(s)}{W(s)} = \underline{\hspace{2cm}}$$

[4 pts] b. Find the transfer function $\frac{Y(s)}{W(s)}$ in terms of D, G, H_y .

$$\frac{Y(s)}{W(s)} = \underline{\hspace{2cm}}$$

[10 pts] c. For the system above, let $D(s) = k_p$, $H_y(s) = 1$, and $G(s) = \frac{2\pi}{s+2\pi}$.

With input $r(t) = r_o u(t)$, and step disturbance $w(t) = w_o u(t)$ determine trend of $y(t)$ as $t \rightarrow \infty$.

$$y(t) \rightarrow \underline{\hspace{2cm}}$$

[10 pts] d. For the system above, let $D(s) = k_p$, $H_y(s) = 1$, and $G(s) = \frac{2\pi}{s+2\pi}$.

With input $r(t) = 0$, and disturbance $w(t) = \cos(2\pi t)u(t)$, determine the sinusoidal steady state response for $y(t)$ after transients have decayed. (Hint: $y(t)$ will be of the form $M \cos(2\pi t + \phi)$. Determine M and ϕ .)

$$y(t) \approx \underline{\hspace{10em}}$$

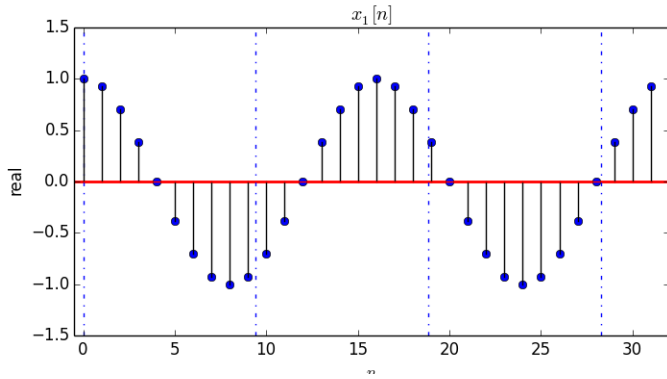
[10 pts] e. For the system above, let $D(s) = \frac{k_p+k_d s}{s^2+4\pi^2}$, $H_y(s) = 1$, and $G(s) = \frac{2\pi}{s+2\pi}$.

With input $r(t) = 0$, and disturbance $w(t) = \cos(2\pi t)u(t) + 0.5u(t)$, determine the steady state response for $y(t)$ after transients have decayed.

$$y(t) \approx \underline{\hspace{10em}}$$

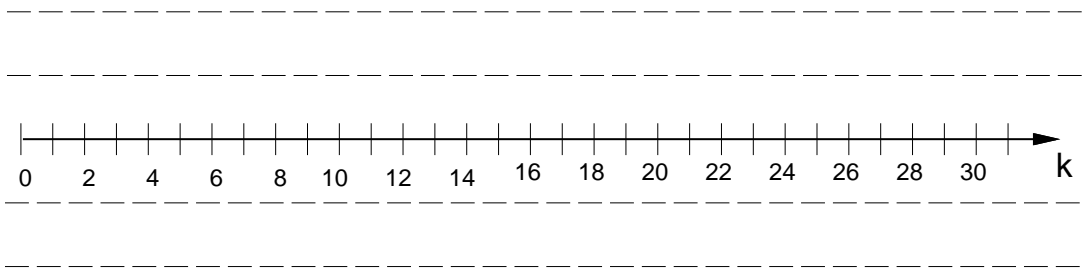
Problem 7. DFT problem (30 pts)

[10 pts] a. Given $x_1[n] = \cos(2\pi \frac{n}{16})$ as shown:

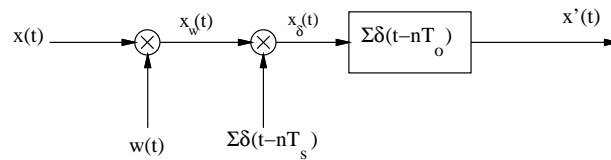


sketch $X_1[k]$, the 32 point DFT of $x_1[n]$, labelling amplitudes.

$X_1[k]$:



The equivalent signal processing operations for a windowed DFT can be represented by the following block diagram:

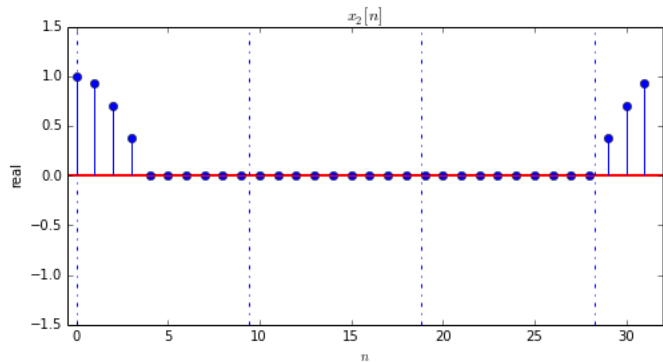


[2 pts] b. For $x_1[n]$ as given above, what are possible T_s and T_o ?

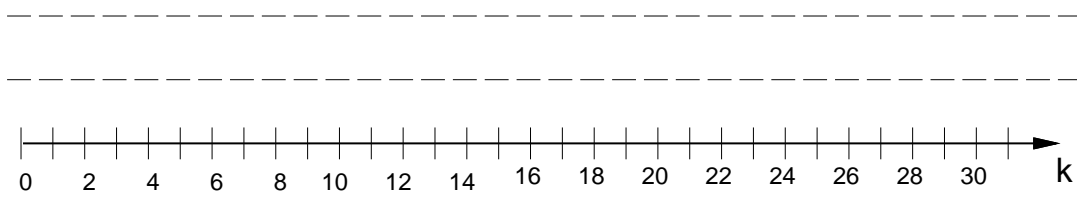
$T_s =$ _____ $T_o =$ _____

[2 pts] c. For $X_1[k]$, and your T_o above, what is the equivalent spacing of the frequency samples?
 spacing = _____ radians/second

[16 pts] d. Given $x_2[n] = \cos(2\pi\frac{n}{16})w[n]$ as shown:



sketch $X_2[k]$, the 32 point DFT of $x_2[n]$, approximately labelling key amplitudes.



$X_2[k]$: -----

Area for scratch work.