

UNIVERSITY OF CALIFORNIA  
College of Engineering  
Electrical Engineering and Computer Sciences Department  
145M Microcomputer Interfacing Lab  
Final Exam Solutions      May 20, 1994

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- 1a**    **Comparator circuit:** Circuit with two analog inputs and one digital input. The output state is determined from the relative value of the two inputs. Usually consists of a differential amplifier with very high gain and voltage limited outputs.
- 1b**    **Harmonic** (of a periodic signal): Component of the signal that has an exact whole number multiple of the fundamental frequency of the signal itself. The complex amplitudes of the harmonic components can be determined from the Fourier transform of the signal.
- 1c**    **Data bus** (for connecting 2 or more parallel outputs): Hardware circuit where a number of parallel outputs can be selectively connected to a common set of parallel signal lines called a bus. Only one parallel output can be asserted on the bus at any one time.
- 1d**    **Differential Linearity Error** (of an A/D converter): The difference between the step sizes and the average step size. Each step is the difference between neighboring transition voltages.
- 1e**    **Fourier Convolution Theorem:** The Fourier transform of the convolution of two functions is the simple product of the Fourier transforms of the two functions.
- 1f**    **Spectral Leakage** (as seen in the FFT of a periodic signal): When a frequency component of a signal does not have a whole number of cycles in the sampling window, the discontinuity at the edges of the window generates frequency components not present in the original signal. This appears as leakage into the adjoining Fourier coefficients and can be described by convolving the true Fourier transform with the Fourier transform of a the rectangular sampling window.
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- 2a**
- 1    Set  $i1 = 0$ .
  - 2    Output the number  $i1$  on the parallel output port
  - 3    The D/A produces an analog voltage that appears on all 8 A/D inputs
  - 4    Using parallel output port #1, output a start pulse
  - 5    All eight A/D converters convert the D/A output
  - 6    When each A/D finishes, its "done" pulse latches the 12 bits of data onto its 12-bit register
  - 7    The program waits a bit more than  $11 \mu s$  for all A/Ds to finish converting
  - 8    Set  $i2 = 1$
  - 9    The program selects tri-state buffer # $i2$  and de-selects the other 7 tri-state buffers by outputting a number on parallel output port #2 which has a 1 in bit position # $i2$  and a 0 in the other 7 positions.
  - 10    The program reads the input port to obtain the output of A/D # $i2$  and saves it in a temporary memory location
  - 11    If the result of step 10 has changed from the last value of the D/A input  $i1$ , save the D/A voltage value that corresponds to  $i1$  as a transition voltage for A/D # $i2$ .
  - 12    Set  $i2 = i2 + 1$  and loop back to step 9 until  $i2 = 8$
  - 13    Set  $i1 = i1 + 1$  and loop back to step 2 until  $i1 = 65,535$  (i.e.  $2^{16} - 1$ )
  - 14    Set  $i2 = 1$
  - 15    For A/D converter # $i2$ , compute the difference between each transition voltage and its ideal value (the absolute error). Determine the maximum value (the maximum absolute error).
  - 16    Subtract neighboring transition voltages to produce a table of step sizes and determine minimum and maximum values of step sizes for A/D converter # $i2$
  - 17    Set  $i2 = i2 + 1$  and loop back to step 15 until  $i2 = 8$
- (another way to find step sizes is to count the number of D/A inputs that produce the same A/D output.)
- [10 points off if only 12 D/A bits are used, since this approach cannot accurately measure transition voltages]

**2b** The outer i1 loop is executed 65k times. The inner loop involves writing to the D/A and producing a A/D start signal (10  $\mu$ s), waiting for the A/Ds to convert (11  $\mu$ s), and selecting and reading all eight tri-state buffers 8 x (10  $\mu$ s + 10  $\mu$ s) for a total of 181  $\mu$ s. The total procedure takes 65k x 181  $\mu$ s = 12 s. [any answer between 10 and 20 sec got full credit]

**3a** The frequency index extends from  $n = 0$  to  $n = 2^{20} = 1049k$ . The highest frequency has index 524k and corresponds to the Nyquist limit of 5 kHz. The amplitude spectrum (Figure 1) has three major components

- (1) The harmonics of the data signal, which appear at  $n = k 100$  (where  $k$  is the harmonic number), because the fundamental has 100 cycles in the 100 s sampling window. [7 points off if omitted]
- (2) A white noise background that adds equally into all Fourier amplitudes. (Actually, the FFT of white noise is itself noisy, but we ignore that complication.) [4 points off if omitted]
- (3) The effect of the low pass filter, which decreases all Fourier amplitudes sharply from 2,000 Hz (the maximum frequency of interest) to 5 kHz (the Nyquist limit). [4 points off if omitted]

Data signal harmonics every 1 Hz ( $n = 100$ ) (exact amplitudes depend on signal)

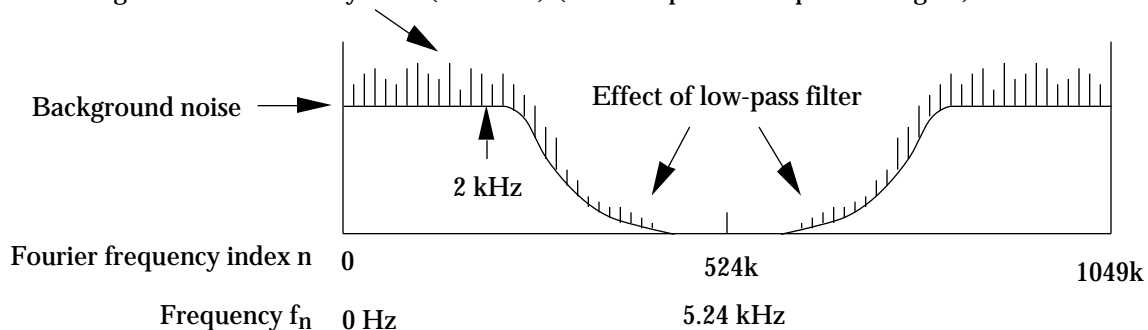


Figure 1. FFT of filtered (data signal plus random background)

**3b** The first Fourier magnitude  $M_1$  corresponds to  $f_1 = 1/100 \text{ s} = 0.01 \text{ Hz}$ .

**3c** The low pass filter must have a gain near unity for  $f \leq 2 \text{ kHz}$  and a very low gain for  $f \geq 5 \text{ kHz}$  to reduce background noise and to prevent aliasing at the sampling frequency of 10 kHz.

**3d** There is no spectral leakage for the data signal, since exactly 100 periods are present. Spectral leakage does not affect the random background noise. Therefore a Hanning window would not help.

- 3e**
- 1 Set data acquisition module for 100 s of sampling at 10,486 Hz.
  - 2 Sample 1,048,486 values
  - 3 take the FFT
  - 4 compute the Fourier magnitudes  $M_n$ ,  $n = 0$  to 524k
  - 5 compute  $A$  as the average of all  $M_n$  values, where  $n$  is not an integer multiple of 100
  - 6 compute 10,490 new Fourier magnitudes  $P_k = M_{100k} - A$
  - 7 take the inverse FFT of  $P_k$  to recover one cycle of the data signal
- [2 points off if a single cycle data signal is not generated as the answer]

- 4**
- |   |                             |   |   |   |   |
|---|-----------------------------|---|---|---|---|
| 1 | Successive approximation    | b | d | g | h |
| 2 | Tracking                    | a | g | h | i |
| 3 | Dual slope (or integrating) | a | f | h | i |
| 4 | Flash                       | c | e | h |   |
- (an answer of 'c' was allowed in line 2 because the item was unclear)

[one point off for each correct letter missing] [one point off for each incorrect letter present]

<b>5</b>	1	RS-232	a	c	e		
	2	RS-422	a	e	f	h	
	3	IEEE-488 (GPIB)	b	e	f		
	4	VME	b	d	e	f	g

If you entered g, it was assumed that you also meant f and e

If you entered f, it was assumed that you also meant e

[0.5 point off for each correct letter missing] [0.5 point off for each incorrect letter present]

**145M Final Exam:**

Problem	1	2	3	4	5	Total
Average	38.6	45.0	51.1	24.2	13.1	171.9
rms	4.1	7.4	5.7	3.7	2.1	13.7
Maximum	42	50	60	32	16	200

**145M Numerical Grades (passing students only):**

	5/8 x Lab	Lab Partic.	Midterm #1	Midterm #2	Final	Total
Average	450	100	92	73	172	887 (B+)
rms	22	0	5	16	14	37
Maximum	500	100	100	100	200	1000

**145M Letter Grade Distribution (passing students only)**

Letter Grade	Course Totals (1000 max)
A+	950.1
A	910.6, 911.8, 912.4, 912.8, 915.6, 943.5
A-	899.7, 901.5, 902.8, 904.5,
B+	884.4, 885.8, 894.8
B	858.4, 873.4
B-	821.0, 824.1, 834.3, 841.5, 848.9